

1.2.0. FIRST ORDER DIFFERENTIAL EQUATIONS:

Most general form

$$\frac{dy}{dx} = f(x, y) = -\frac{P(x, y)}{Q(x, y)} \dots \dots \dots (2.1.0)$$

$$\text{or } P(x, y)dx + Q(x, y)dy = 0 \dots \dots \dots (2.2.0)$$

A number of such equations exist in physical sciences.
special form

$$\text{let } \frac{dy}{dx} = f(x, y) = -\frac{P(x)}{Q(y)} \dots \dots \dots (2.3.0)$$

$$\text{then } P(x)dx + Q(y)dy = 0$$

$$\text{By integration } \int_{x_0}^x P(x)dx + \int_{y_0}^y Q(y)dy = 0 \dots \dots \dots (2.4.0)$$

We may ignore lower limits x_0 & y_0 which contribute to constants and simply add a constant.

Note! This separation of variable does not require that the differential eqⁿ be linear.

Ex: Boyle's law
In differential form $\frac{dV}{dP} = -\frac{V}{P}$ ($T = \text{constant}$)

$$\text{or } \frac{dV}{V} = -\frac{dP}{P}$$

$$\text{Integrating } \ln V = -\ln P + C$$

$$\text{or } \ln PV = \ln K \quad \text{i.e. } PV = K$$

Separable variable Equation:- $\dots \dots \dots (2.5.0)$

$$\frac{dy}{dx} = f(x)g(y)$$

$$\text{Here } \int \frac{dy}{g(y)} = \int f(x)dx$$

If the integrals can be evaluated we get $y(x)$ satisfying (2.5.0).
Note! Some ODE can be reduced to the form (2.5) after appropriate factorisation.

$$\text{Ex. } \frac{dy}{dx} = x + xy = x(1+y)$$

$$\text{or } \int \frac{dy}{1+y} = \int x dx$$

$$\therefore \ln(1+y) = \frac{x^2}{2} + C \rightarrow \text{const.}$$

$$\text{or } (1+y) = \exp\left(\frac{x^2}{2} + C\right) = A \exp \frac{x^2}{2} \quad \text{where } A = \exp(C)$$

Solution Method

1. Factorise the eqn so that it becomes separable
2. Rearrange terms involving x and y in opposite sides and integrate directly.
3. Constants of integration may be determined with further information (e.g. boundary cond.)

Exact Differential Equations:

Consider $P(x,y)dx + Q(x,y)dy = 0 \dots \dots \dots (2.1.0)$

This eqn is exact if it can be matched with differential $d\phi$

$$d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy$$

As eqn. 2.1. has '0' on the right

$$\frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy = 0$$

i.e. $\phi(x,y) \Rightarrow$ the unknown $f^n = \text{constant}$

$$\text{Thus } P(x,y)dx + Q(x,y)dy = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy$$

$$\therefore \left. \begin{aligned} P(x,y) &= \frac{\partial \phi}{\partial x} \\ Q(x,y) &= \frac{\partial \phi}{\partial y} \end{aligned} \right\} \dots \dots \dots (2.6.0)$$

$$\therefore \frac{\partial P}{\partial y} = \frac{\partial^2 \phi}{\partial y \partial x} = \frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial Q}{\partial x}$$

$$\therefore \boxed{\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}} \dots \dots \dots (2.7.0)$$

This has some resemblance with equations involved in potential theory.

If $\phi(x,y)$ exists then our solution is

$$\phi(x,y) = C \dots \dots \dots (2.8.0)$$

From (2.6) $\phi(x,y) = \int P(x,y)dx + F(y) \dots \dots \dots (2.9)$

The function $F(y)$ can be found from (2.6) by differentiating (2.9) w.r.t y and equating to $Q(x,y)$

Ex. solve $x \frac{dy}{dx} + 3x + y = 0$

Rearranging $(3x+y)dx + xdy = 0$

Here $P(x,y) = 3x+y \quad \therefore \frac{\partial P}{\partial y} = 1 = \frac{\partial Q}{\partial x}$

$Q(x,y) = x$

and the eqn is exact.

Hence the solution is given by (2.9)

$$\phi(x,y) = \int (3x+y)dx + F(y) = C_1$$

$$\text{or } \frac{3x^2}{2} + xy + F(y) = C_1$$

Now $\frac{\partial \phi}{\partial y} = \frac{\partial F(y)}{\partial y} + x = Q(x, y) = x$

Thus $\frac{\partial F(y)}{\partial y} = 0$ or $F(y) = C_2$

Thus $\phi(x, y) = \frac{3x^2}{2} + xy + C_2 = C_1$

or $\frac{3x^2}{2} + xy = C \Rightarrow$ solution of original ODE.

Method of Solution: (i) check if the eqn is exact using 2.7.

(ii) solve using 2.9

(iii) Find $F(y)$ by differentiating 2.9 w.r.t y and using 2.6.

1.2.1. INEXACT EQUATIONS:-

The equations may be written in the form

$$P(x, y)dx + Q(x, y)dy = 0 \text{ but } \frac{\partial P}{\partial y} \neq \frac{\partial Q}{\partial x}$$

and are called inexact equations.

Here the differential can be made exact by multiplying by a factor called integrating factor ($\mu(x, y)$ say)

which obeys $\frac{\partial}{\partial y}(\mu P) = \frac{\partial}{\partial x}(\mu Q) \dots \dots \dots (2.11)$

There exists no general methods for finding the integrating factor $\mu(x, y)$. Sometimes it may be found by inspection. However if an integrating factor exists which is a f^n of x or y alone then eqn. 2.1.1 can be solved to find it.

Let $\mu = \mu(x)$

Then $\mu(x)P(x, y)dx + \mu(x)Q(x, y)dy = 0$

and eqn. 2.1.1 reads as

$$\mu(x) \frac{\partial P}{\partial y}(x, y) = Q(x, y) \frac{\partial \mu(x)}{\partial x} + \mu(x) \frac{\partial Q}{\partial x}(x, y)$$

or $\left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x}\right) = \frac{Q}{\mu} \frac{d\mu}{dx}$

or $\frac{d\mu}{\mu} = \frac{1}{Q} \left(\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x}\right) dx = f dx$

or $\ln \mu = \int f dx \dots \dots \dots (2.1.2)$

If we insist that $f = f(x)$ only

then $\mu(x) = \exp \left[\int f(x) dx \right]$

with $f(x) = \frac{1}{Q} \left[\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right] \dots \dots \dots (2.1.3)$

similarly if $\mu = \mu(y)$

$\mu(y) = \exp \left[\int g(y) dy \right] \dots \dots \dots (2.1.4)$

where $g(y) = \frac{1}{P} \left[\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] \dots \dots \dots (2.1.5)$

Ex: $\frac{dy}{dx} = -\frac{2}{y} - \frac{3y}{2x} \dots \dots \dots (2.1.6)$

Rearranging $\frac{dy}{dx} = \frac{-4x - 3y^2}{2xy}$

or $2xy dy = -4x dx - 3y^2 dx$

or $2xy dy + (3y^2 + 4x) dx = 0 \dots \dots \dots (2.1.7)$

Here $Q = 2xy$; $P = 3y^2 + 4x$

and $\frac{\partial P}{\partial y} = 6y \neq \frac{\partial Q}{\partial x} (= 2y)$

Thus the ODE is inexact

However, we notice that

$$\frac{1}{Q} \left[\frac{\partial P}{\partial y} - \frac{\partial Q}{\partial x} \right] = \frac{1}{2xy} [6y - 2y] = \frac{2}{x}$$

$$\Rightarrow f^n \text{ of } x \text{ alone} = f(x)$$

Hence there exists an integrating factor which is a function of x alone given by

$$\begin{aligned} \mu(x) &= \exp \left[\int f(x) dx \right] = \exp \left[\int \frac{2}{x} dx \right] = \exp [2 \ln x] \\ &= \exp [\ln x^2] = x^2 \end{aligned}$$

Multiplying eqn 2.1.7 by x^2 we get

$$x^2(3y^2 + 4x) dx + x^2(2xy) dy = 0$$

$$\text{or } (3x^2y^2 + 4x^3) dx + 2x^3y dy = 0$$

or integrating we get

$$x^4 + x^3y^2 = c$$

$$\text{or } x^4 + x^3y^2 = c$$



\Rightarrow soln of original eqn



or

$$\begin{aligned} \phi(x,y) &= \int P(x,y) dx + F(y) \\ &= \int (4x^3 + 3x^2y^2) dx + F(y) \\ &= x^4 + x^3y^2 + F(y) + C_1 \end{aligned}$$

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= 2x^3y + \frac{\partial F}{\partial y} \\ &= Q(x,y) = 2x^3y \end{aligned}$$

$$\therefore \frac{\partial F}{\partial y} = 0$$

$$\text{Hence } \phi(x,y) = x^4 + x^3y^2 + C$$

Method of soln:

- Examine if $f(x)$ and $g(y)$ are f^n s of only x or y
- If so, then the integrating factor is a f^n of either x or y and is given by eqn 2.1.3 & 2.1.5
- If the integrating factor is a f^n of x & y , then it may sometimes be found by inspection or by trial and error.
- In any case the integrating factor must satisfy eq. 2.1.1.
- Once the eqn has been made exact. solve by the method of section 2.1.

1.2.2. Linear First Order Differential Equations:-

consider the eqn 2.1

$$\frac{dy}{dx} = f(x, y) \quad \dots \quad 2.1$$

$$\text{If } f(x, y) = -p(x)y + q(x) \quad \dots \quad 2.2.1$$

$$\text{then } \frac{dy}{dx} = -p(x)y + q(x)$$

$$\text{or } \frac{dy}{dx} + p(x)y = q(x) \quad \dots \quad 2.2.2$$

This is the most general linear first order DE.

If $q(x) = 0$, eq. (2.2.2) is homogeneous.

$q(x) \neq 0$ gives a source term or a driving term.

Eq. (2.2.2) is linear, each term is linear in y or $\frac{dy}{dx}$. There are no higher powers i.e. y^2 and no products i.e. $y \frac{dy}{dx}$. Note that the linearity refers to independent variable y and $\frac{dy}{dx}$, $p(x)$ and $q(x)$ need not be linear in x . Eq. (2.2.2), the most important of the first DE in physics may be solved exactly.

The equation can be made exact by multiplying throughout by an appropriate integrating factor $\mu(x)$ such that

$$\mu(x) \frac{dy}{dx} + \mu(x)p(x)y = \mu(x)q(x) \quad \dots \quad 2.2.3$$

may be rewritten as

$$\frac{d}{dx} [\mu(x)y] = \mu(x)q(x) \quad \dots \quad 2.2.4$$

The purpose of this is to make the left side of eq. (2.2.2) a derivative so that it can be integrated by inspection. It also incidentally, makes eq. 2.2.2 exact.

Expanding eq. (2.2.4) we get

$$\mu(x) \frac{dy}{dx} + \frac{d\mu}{dx} y = \mu(x)q(x)$$

Comparison with eqn (2.2.3) shows that we must require

$$\mu(x) \frac{dy}{dx} + \frac{d\mu}{dx} y = \mu(x) \frac{dy}{dx} + \mu(x)p(x)y$$

$$\text{i.e. } \frac{d\mu}{dx} = \mu(x)p(x) \quad \dots \quad 2.2.5$$

This is a D.E for $\mu(x)$ with μ and x separable.

$$\frac{d\mu}{\mu} = p(x)dx \quad \text{or } \mu = e^{\int p(x)dx} \quad \dots \quad 2.2.6$$

μ is the integrating factor.

With this we proceed to integrate eq. 2.2.4 which is what we want

$$\text{Here } \int \frac{d}{dx} [\mu(x)y] dx = \int \mu(x)q(x) dx$$

$$\text{or } \mu(x)y = \int \mu(x)q(x) dx + C$$

$$\therefore y(x) = \left[\mu(x) \right]^1 \left\{ \int \mu(x) v(x) dx + c \right\} \dots 2.2.7$$

with $\mu(x) = e^{\int p(x) dx}$ we have finally

$$y(x) = e^{-\int p(x) dx} \left[\int q(x') e^{\int p(x') dx'} dx' + c \right] \dots 2.2.8$$

Eq 2.2.8 is the most general soln of eqⁿ 2.2.2. The soln 2.2.9 $y_1(x) = c e^{-\int p(x) dx}$ corresponds to the case $q(x)=0$ and is a general solution of the homogeneous DE.

The other term in eq. 2.2.7

$$y_2(x) = \left[e^{-\int p(x) dx} \right] \int q(x') e^{\int p(x') dx'} dx' \dots 2.2.10$$

is a particular solution corresponding to specific source term $q(x)$.

Note: Linear first order DE is separable if it is homogeneous [i.e. $q(x)=0$]. Otherwise, except for special cases like $p=\text{const}$; $q=\text{const}$ or $q(x)=\lambda p(x)$; eq(2.2.2) is not separable.

Ex. $\frac{dy}{dx} = 4x - 2xy$ Here $p(x) = 2x$ and integrating factor is $\mu(x) = e^{\int p(x) dx}$

$$\text{or } \mu(x) = e^{\int 2x dx} = e^{x^2}$$

Multiplying by x^2 the DE becomes $e^{x^2} \frac{dy}{dx} + 2xy e^{x^2} = 4x e^{x^2}$

$$\text{or } \frac{d}{dx} [y e^{x^2}] = 4x e^{x^2} \Rightarrow y e^{x^2} = \int 4x e^{x^2} dx + c = 4 \int e^{x^2} x dx + c$$

$$= 2 \int e^{x^2} d(x^2) + c = 2 e^{x^2} + c$$

Thus the soln of the ODE is $y = 2 + c e^{-x^2}$

Ex. LR circuit: For a circuit containing resistance and inductance

Kirchoff's law gives $L \frac{dI(t)}{dt} + RI(t) = V(t)$

$V(t) = \text{Voltage}$

$I(t) = \text{current at time } t$

or $\frac{dI(t)}{dt} + \frac{R}{L} I(t) = \frac{1}{L} V(t)$ The I.F. is

$$\mu(t) = e^{\int \frac{R}{L} dt} = e^{\frac{Rt}{L}}$$

Hence by eq. 2.2.7

$$I(t) = e^{-\frac{Rt}{L}} \left[\int e^{\frac{Rt}{L}} \frac{V(t)}{L} dt + c \right]$$

c is to be determined from boundary cond.

For $V(t) = V_0 = \text{constant}$

$$I(t) = e^{-\frac{Rt}{L}} \left[\frac{V_0}{L} \int e^{\frac{Rt}{L}} dt + c \right] = e^{-\frac{Rt}{L}} \left[\frac{V_0}{L} \frac{L}{R} e^{\frac{Rt}{L}} + c \right]$$

$$= \frac{V_0}{R} + c e^{-\frac{Rt}{L}}$$

If initial condition gives $I(0) = 0$ then $c = -\frac{V_0}{R}$

$$\text{and } I(t) = \frac{V_0}{R} \left[1 - e^{-\frac{Rt}{L}} \right]$$

1.3. HOMOGENEOUS EQUATIONS:

Homogeneous equations are ODE's written in the form

$$\frac{dy}{dx} = \frac{P(x,y)}{Q(x,y)} = F\left(\frac{y}{x}\right) \quad \dots \quad 1.3.1.$$

where $P(x,y)$ & $Q(x,y)$ are homogeneous functions of identical degree.

A f^n $f(x,y)$ is homogeneous of degree n if for any λ , it obeys

$$f(x, \lambda y) = \lambda^n f(x, y)$$

$$\left. \begin{array}{l} P(x,y) = x^2y - xy^2 \\ Q(x,y) = x^3 + y^3 \end{array} \right\} \text{are homogeneous in } x \text{ \& } y \text{ and of degree 3.}$$

For $P(x,y)$ & $Q(x,y)$ both to be homogeneous and of same degree the sum of powers of x and y should be identical for each term in P and Q .

The RHS of a homogeneous f^n can be written as a f^n of y/x .

$$\text{let } \frac{dy}{dx} = F\left(\frac{y}{x}\right)$$

$$\text{substitute } y = vx$$

$$\therefore \frac{dy}{dx} = x \frac{dv}{dx} + v = F(v)$$

This is separable as the transformed eqn is

$$x \frac{dv}{dx} + v = F(v)$$

$$\text{or } x \frac{dv}{dx} = F(v) - v \Rightarrow \frac{dv}{F(v) - v} = \frac{dx}{x} \quad \dots \quad 1.3.2$$

Direct integration gives the soln of the ODE depending on the form of $F(v)$

Ex. $\frac{dy}{dx} = \frac{y}{x} + \tan\left(\frac{y}{x}\right)$

$$\text{Put } y = vx$$

$$\therefore v + x \frac{dv}{dx} = v + \tan v$$

$$\therefore \int \frac{dv}{\tan v} = \int \frac{dx}{x} \Rightarrow \int \cot v dv = \ln x + c_1$$

$$\text{But } \int \cot v dv = \int \frac{\cos v dv}{\sin v} = \int \frac{d(\sin v)}{\sin v} = \ln(\sin v) + c_2$$

$$\text{Hence } \ln \sin v = \ln x + c_1 - c_2$$

$$\therefore \ln\left(\frac{\sin v}{x}\right) = \ln A \text{ say}$$

$$\text{OR } \frac{\sin v}{x} = A \quad \text{const.} \Rightarrow v = \sin^{-1}(Ax)$$

$$\therefore y = vx = x \sin^{-1}(Ax) \Rightarrow \text{soln of DE.}$$

Method

- check if the eqⁿ is homogeneous
- If so, substitute $y = vx$, the separate variables as in 1.3.2. and integrate directly.
- Finally replace v by y/x to get the soln.

1.4. BERNOULLI'S EQUATION :-

$$\frac{dy}{dx} + p(x)y = q(x)y^n \quad n \neq 0 \text{ or } 1 \quad \dots \dots \dots 1.4.1$$

For $n=0$ or 1 it is linear

The eqⁿ is non linear due to the term y^n

This eqⁿ can be made linear by the transformation

$$v = y^{1-n}$$

$$\text{Then } \frac{dv}{dx} = (1-n)y^{-n} \frac{dy}{dx}$$

$$\therefore \frac{dy}{dx} = \frac{y^n}{1-n} \frac{dv}{dx}$$

substitution in eq. (1.4.1) gives

$$\left(\frac{y^n}{1-n}\right) \frac{dv}{dx} + p(x) \frac{v}{y^{-n}} = q(x) \frac{v}{1-2n}$$

$$\text{OR } \frac{dv}{dx} + (1-n)p(x)v = (1-n)q(x)$$

which is a linear equation and may be solved by choosing appropriate integrating factor.

Ex. $\frac{dy}{dx} + \frac{y}{x} = 2x^3y^4 \Rightarrow$ let $v = y^{1-4} = y^{-3}$ then $\frac{dy}{dx} = \frac{dy}{dv} \cdot \frac{dv}{dx} = -\frac{y^4}{3} \frac{dv}{dx}$

$$\therefore -\frac{y^4}{3} \frac{dv}{dx} + \frac{vy^4}{x} = 2x^3y^4 \Rightarrow \frac{dv}{dx} - \frac{3v}{x} = -6x^3$$

$$\text{Take the I.F} = \exp\left[-3 \int \frac{dx}{x}\right] = \exp[-3 \ln x] = \frac{1}{x^3}$$

$$\text{This yields } \frac{v}{x^3} = -6x + c \quad \therefore y^{-3} = -6x^4 + cx^3 \Rightarrow \text{soln.}$$

Note: There are many other types of first order DE which we just skip.

1.5. MISCELLANEOUS EQ^N.

Consider the type

$$\frac{dy}{dx} = F(ax+by+c) \quad \dots \dots \dots 1.5.1$$

→ solve by change of variable method

Put $v = ax+by+c$

$$\frac{dv}{dx} = a + b \frac{dy}{dx}$$

$$\text{Eq. 1.5.1} \Rightarrow \frac{1}{b} \left(\frac{dv}{dx} - a \right) = F(v)$$

$$\text{or } \frac{dv}{dx} = bF(v) + a$$

This is separable and may be integrated directly.

Ex. $\frac{dy}{dx} = (x+y+1)^2$

put $v = x+y+1$

$$\therefore \frac{dv}{dx} = \frac{dy}{dx} + 1 \Rightarrow \frac{dv}{dx} = v^2 + 1 \quad \text{or } \frac{dv}{1+v^2} = dx$$

∴ integrating we get

$$\tan^{-1}(v) = x + C_1$$

$$\text{or } \tan^{-1}(x+y+1) = x + C_1$$

The soln of DE is $\tan^{-1}(x+y+1) = x + C_1$

Ex. Flow of water from an orifice in a tank.

Here velocity $v = \sqrt{2gh}$

Volume of water ΔV escaping in Δt

$$\Delta V = v A \Delta t \quad A = \text{Area of the hole}$$
$$= \sqrt{2gh} \frac{\pi d^2}{4} \Delta t$$

Volume lost in water \approx level of tank

$$\Delta V = \frac{\pi D^2}{4} \Delta h$$

$$\therefore -\frac{\pi D^2}{4} \Delta h = \sqrt{2gh} \frac{\pi d^2}{4} \Delta t$$

$$\text{or } \frac{dh}{dt} = -\sqrt{2gh} \frac{d^2}{D^2} = -\frac{d^2}{D^2} \sqrt{2g} \sqrt{h} \quad \text{or } \frac{dh}{h^{1/2}} = -\frac{d^2}{D^2} \sqrt{2g} \cdot dt$$

$$\text{Integrating } 2h^{1/2} = -\frac{d^2}{D^2} \sqrt{2g} \cdot t + C$$

$$\text{or } h^{1/2} = -\frac{d^2}{D^2} \sqrt{g/2} t + C$$

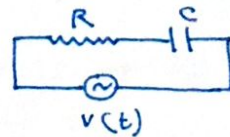
Boundary cond. $h = h_0$ at $t = 0$

$$\therefore C = h_0^{1/2}$$
$$\text{Hence } h(t) = \left[-\frac{d^2}{D^2} \sqrt{\frac{g}{2}} t + \sqrt{h_0} \right]^2$$

$$h(t) = 0 \text{ at } t = \frac{D^2}{d^2} \sqrt{\frac{2h_0}{g}} \text{ sec.}$$

Ex: In a resistance capacitor series circuit the charge q on the capacitor is given by

$$R \frac{dq}{dt} + \frac{q}{C} = V(t)$$



Boundary condition at $t=0$, $q=0$
and $V(t) = V_0 \sin \omega t$

Here $\frac{dq}{dt} + \frac{1}{RC} q = \frac{V(t)}{R}$

Here I.F is $\exp \left[\int \frac{1}{RC} dt \right] = e^{t/RC}$

Thus the soln is given by $q(t) = e^{-t/RC} \left[\int \frac{V(t)}{R} e^{t/RC} dt + C_1 \right]$

If $V(t) = \text{const} = V_0$ then

$$q(t) = e^{-t/RC} \left[\frac{V_0}{R} \int e^{t/RC} dt + C_1 \right] = e^{-t/RC} \left[\frac{V_0}{R} \cdot RC e^{t/RC} + C_1 \right]$$

$$= q_0 + C_1 e^{-t/RC}$$

At $t=0$, $q=0 \therefore C_1 = -q_0$

$$\therefore q(t) = q_0 [1 - e^{-t/RC}] \Rightarrow \text{condenser charging}$$

If $V(t) = V_0 \sin \omega t$
then $q(t) = e^{-t/RC} \left[\int \frac{V(t)}{R} e^{t/RC} dt + C_1 \right]$

If $V(t) = V_0 \sin \omega t$

$$\int \frac{V(t)}{R} e^{t/RC} dt = \left(\frac{V_0}{R} \right) \int \sin \omega t e^{t/RC} dt = \frac{V_0}{R} I$$

where $I = \int \sin \omega t e^{t/RC} dt$

$$I = \left[RC \sin \omega t e^{t/RC} - \omega RC \int \cos \omega t e^{t/RC} dt \right]$$

$$= \left[RC \sin \omega t e^{t/RC} - \omega RC \left\{ RC \cos \omega t e^{t/RC} + \omega RC \int \sin \omega t e^{t/RC} dt \right\} \right]$$

$$= RC \sin \omega t e^{t/RC} - \omega R^2 C^2 \cos \omega t e^{t/RC} - \omega^2 R^2 C^2 I$$

Thus $(1 + \omega^2 R^2 C^2) I = \{ RC \sin \omega t - \omega R^2 C^2 \cos \omega t \} e^{t/RC}$

$$\therefore I = (1 + \omega^2 R^2 C^2)^{-1} \{ RC \sin \omega t - \omega R^2 C^2 \cos \omega t \} e^{t/RC}$$

$$\text{Hence } q(t) = e^{-t/RC} \left[\frac{V_0}{R} (1 + \omega^2 R^2 C^2)^{-1} RC \{ \sin \omega t - \omega RC \cos \omega t \} e^{t/RC} + C_1 \right]$$

$$= q_0 (1 + \omega^2 R^2 C^2)^{-1} (\sin \omega t - \omega RC \cos \omega t) + C_1 e^{-t/RC}$$

Applying boundary condition viz at $t=0$, $q=0$, $C_1 = q_0 (1 + \omega^2 R^2 C^2)^{-1} \omega RC$
Thus $q(t) = \left[q_0 (1 + \omega^2 R^2 C^2)^{-1} \{ \sin \omega t - \omega RC \cos \omega t \} + q_0 (1 + \omega^2 R^2 C^2)^{-1} \omega RC e^{-t/RC} \right]$
 $= q_0 (1 + \omega^2 R^2 C^2)^{-1} [\sin \omega t + \omega RC \{ e^{-t/RC} - \cos \omega t \}]$

1.6. Most general higher degree first order eqn:-

$$F(x, y, \frac{dy}{dx}) = 0 \quad \dots \quad 1.6.1$$

The most general standard form is

$$p^n + a_{n-1}(x, y)p^{n-1} + \dots + a_1(x, y)p + a_0(x, y) = 0 \quad \dots \quad 1.6.2$$

where $p = \frac{dy}{dx}$

we shall not discuss the solutions of such equations (if it can be solved).